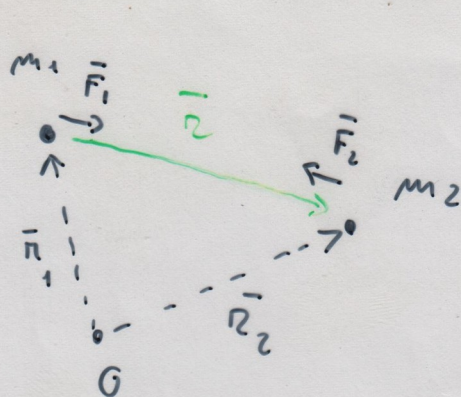


ELEMENTI ORBITALI

- Moto relativo
- Equazione di Keplero
- Trasformazione da elementi orbitali a coordinate cartesiane e viceversa.

EQUAZIONE del MOVO RELATIVO.

o)



$$\vec{r}_1 + \vec{r} = \vec{r}_2$$

$$\vec{r} = \vec{r}_2 - \vec{r}_1$$

$$\vec{F}_1 = G \frac{m_1 m_2}{r^3} \vec{r} = m_1 \ddot{\vec{r}}_1 \quad \text{Forza su } m_1$$

$$\vec{F}_2 = -G \frac{m_1 m_2}{r^3} \vec{r} = m_2 \ddot{\vec{r}}_2 \quad \text{Forza su } m_2$$

$$m_1 \ddot{\vec{r}}_1 + m_2 \ddot{\vec{r}}_2 = 0 \Rightarrow \ddot{\vec{a}}_{CM} \quad (\text{NO FORZE ESTERNE})$$

$$\ddot{\vec{r}} = \ddot{\vec{r}}_2 - \ddot{\vec{r}}_1 = \left(-\frac{G m_1 m_2}{r^3 m_2} - \frac{G m_1 m_2}{r^3 m_1} \right) \vec{r} =$$

$$= -G \frac{(m_1 + m_2)}{r^3} \vec{r}$$

↙

Eq. in \vec{r}

ELEMENTI ORBITALI: DEFINIZIONE

EQUAZIONE del MOTO RELATIVO:
$$\frac{d^2 \vec{r}}{dt^2} + \mu \frac{\vec{r}}{r^3} = 0$$

$$\mu = G(m_1 + m_2)$$

- SISTEMA È ISOLATO → 3-1 GRADI di LIBERTÀ → IL MOTO SI SVOLGE SU UN PIANO.

INTEGRALE MOMENTO ANGOIARE:
$$\vec{h} = \vec{r} \times \dot{\vec{r}}$$

IN COORDINATE POLARI:

- $$\ddot{\vec{r}} = (\ddot{r} - r\dot{\theta}^2) \hat{r} + \left[\frac{1}{r} \frac{d}{dt} (r^2 \dot{\theta}) \right] \hat{\theta}$$

$$\ddot{\vec{r}} + \mu \frac{\vec{r}}{r^3} = 0 \quad \begin{matrix} \nearrow & \ddot{r} - r\dot{\theta}^2 + \mu \frac{r}{r^3} = 0 & \hat{r} \\ \searrow & \frac{1}{r} \frac{d}{dt} (r^2 \dot{\theta}) = 0 & \hat{\theta} \end{matrix}$$

- $$\vec{h} = r^2 \dot{\theta} \hat{z} = \text{CONSTANTE}$$

$$\begin{aligned} \vec{h} &= r \hat{r} \times (\dot{r} \hat{r} + r \dot{\theta} \hat{\theta}) = \\ &= 0 + r^2 \dot{\theta} \hat{z} \end{aligned}$$

$$\left(\ddot{r} - e \dot{\theta}^2 \right) + \frac{\mu}{r^2} = 0 \rightarrow \text{condiziona } r(\theta)$$

variabile ausiliaria $y = \frac{1}{r}$

$$\ddot{r} = -h \frac{dy}{d\theta} \rightarrow \ddot{r} = -h^2 y^2 \frac{d^2 y}{d\theta^2} \rightarrow$$

$$-h^2 y^2 \frac{d^2 y}{d\theta^2} - h^2 y^3 + \mu y^2 = 0 \Rightarrow$$

$$\frac{d^2 y}{d\theta^2} + y = \frac{\mu}{h^2}$$

eq. differenziale a coefficienti costanti

$$y(\theta) = \frac{\mu}{h^2} (1 + e \cos(\theta - \theta_0))$$

$$r(\theta) = \frac{p}{1 + e \cos(\theta - \theta_0)}$$

$$p = \frac{h^2}{\mu}$$

ELLISSI: $p = a(1 - e^2) \quad e < 1$

PARABOLA: $p = 2q \quad e = 1$ con q distanza minima

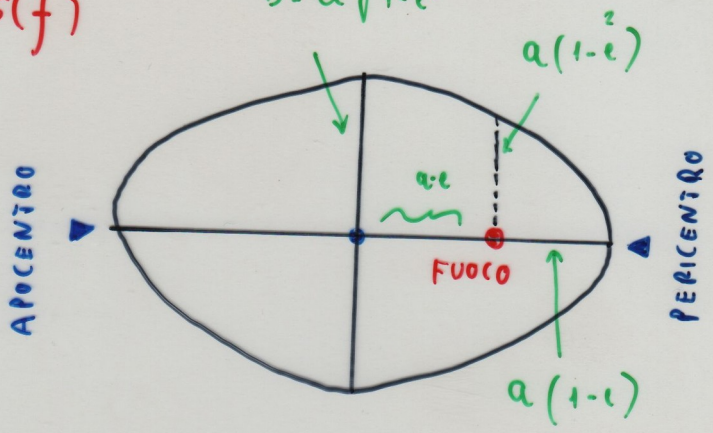
IPERBOLE: $p = a(e^2 - 1) \quad e > 1$

3-

$$r = \frac{a(1-e^2)}{1+e\cos(f)}$$

$f = \text{ANOMALIA VERA}$

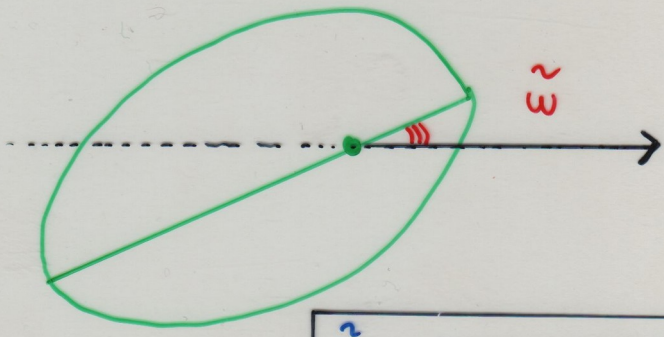
$$b = a\sqrt{1-e^2}$$



$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$\begin{cases} x = a \cos u \\ y = b \sin u \end{cases}$$

• DIREZIONE di RIFERIMENTO :



$\tilde{\omega} = \text{LONGITUDINE del PERICENTRO}$

AREA = πab

PERIMETRO = $4\pi E(e)$

$$E(e) = \int_0^{\frac{\pi}{2}} \sqrt{1-e^2 \sin^2 \theta} d\theta$$

Integrale ellittico completo del 2° tipo.

$$V_{A_2} = \frac{h}{2} \Rightarrow \frac{hT}{2} = \pi ab = \pi a^2 \sqrt{1-e^2}$$

$$h = \sqrt{\mu a(1-e^2)} \rightarrow \frac{h^2}{\mu} = a(1-e^2)$$

$T = 2\pi \sqrt{\frac{a^3}{\mu}}$	PERIODO
$m = \frac{2\pi}{T} = \sqrt{\frac{\mu}{a^3}}$	MOTO MEDIO

COSTANTE del MOTO m^2 : INTEGRALE ENERGIA

$$\frac{1}{2} v^2 - \frac{\mu}{r} = C$$

$$\ddot{r} \cdot \dot{r} + \mu \frac{\dot{r} \cdot \dot{r}}{r^3} = 0$$

$$= \frac{d}{dt} \left(\frac{\dot{r} \cdot \dot{r}}{2} - \frac{\mu}{r} \right)$$

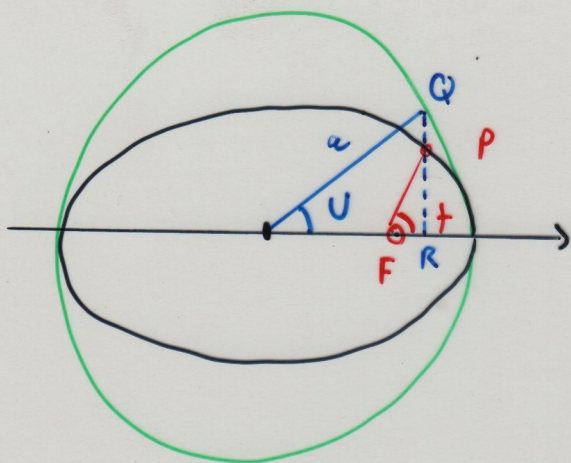
$h =$ INVARIANTE INTEGRALE MOMENTO ANGOLARE

$C =$ INVARIANTE INTEGRALE ENERGIA

- IL SISTEMA HA 3-2 GRADI di LIBERTÀ $\Rightarrow 1$

$M = m(t-t_0)$	ANOMALIA MEDIA
----------------	----------------

EQUAZIONE di KEPLERO



$$1) \quad r(U) \\ t(U)$$

$$2) \quad \text{Eq. che dà} \\ U(t)$$

• 1° OBIETTIVO: Calcolare r, t in funzione di U

$$FR = r \cos f = a \cos U - ae$$

$$PR = r \sin f = \sqrt{1-e^2} a \sin U$$

$$r = a(1 - e \cos U)$$

$$t_g\left(\frac{f}{2}\right) = \left(\frac{1+e}{1-e}\right)^{\frac{1}{2}} t_g\left(\frac{U}{2}\right)$$

$$* \quad \cos f = 1 - 2 \sin^2 \frac{f}{2} \quad r \cos f = r(1 - 2 \sin^2 \frac{f}{2})$$

$$2r \sin^2 \frac{f}{2} = r - r \cos f = a(1 - e \cos U) - a \cos U + ae = a(1+e)(1 - \cos U)$$

$$\cos f = 2 \cos^2 \frac{f}{2} - 1 \Rightarrow 2r \cos^2 \frac{f}{2} = a(1+e)(1 + \cos U)$$

• OBIETTIVO: (CALCOLARE $U(t)$)

$$\dot{r} = \frac{na}{\sqrt{1-e^2}} e \sin f \quad r\dot{f} = \frac{na}{\sqrt{1-e^2}} (1+e \cos f)$$

$$1) \quad \mu \left(\frac{r}{R} - \frac{1}{a} \right) = v^2 = \dot{r}^2 + (r\dot{f})^2$$

$$\dot{r} = \frac{na e \sin f}{\sqrt{1-e^2}}$$

(M-D, pg 31)

$$c = -\frac{\mu}{2a}$$

$$r\dot{f} = \frac{na(1+e \cos f)}{\sqrt{1-e^2}}$$

$$2) \quad \left\{ \begin{aligned} \dot{r} &= \frac{na}{R} \sqrt{a^2 e^2 - (R-a)^2} = \frac{na^2 e \sin U}{a(1-e \cos U)} \\ \dot{r} &= ae \sin U \frac{dU}{dt} \end{aligned} \right. \Rightarrow \frac{dU}{dt} = \frac{n}{(1-e \cos U)}$$

$$\Rightarrow \frac{dU}{dt} = \frac{n}{(1-e \cos U)}$$

3)

$$U - e \sin U = M = n(t-t_0)$$

Equazione di Keplero \Rightarrow Legge Oraria

SOLUZIONE: Metodo iterativo

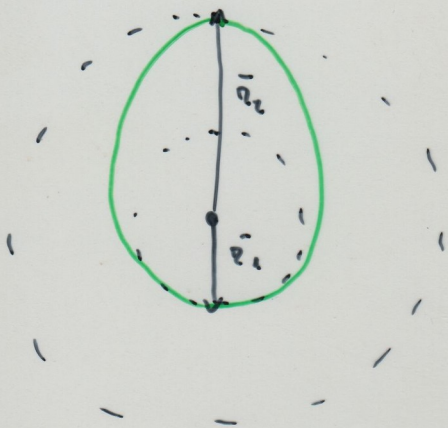
$$U_0 = M$$

$$U_1 = U_0 + e \sin U_0$$

$$U_2 = U_0 + e \sin U_1$$

$$\vdots$$

$$U_{i+1} = M + e \sin U_i$$



ORBITA di TRASFERIMENTO:

$$a(1-e) = r_1$$

$$a(1+e) = r_2$$

$$a(1-e) + a(1+e) = 2a = r_1 + r_2$$

$$a = \frac{r_1 + r_2}{2}$$

$$e = 1 - \frac{r_1}{a}$$

Calcolo del ΔV :

$$V_{C1} = \sqrt{\mu \left(\frac{2}{r_1} - \frac{1}{a} \right)} = \sqrt{\frac{\mu}{r_1}}$$

$$V_{C2} = \sqrt{\frac{\mu}{r_2}}$$

$$V_{P1} = \sqrt{\mu \left(\frac{2}{a(1-e)} - \frac{1}{a} \right)} = \sqrt{\frac{\mu}{a} \left(\frac{1+e}{1-e} \right)}$$

$$V_{A2} = \sqrt{\frac{\mu}{a} \left(\frac{1-e}{1+e} \right)}$$

$$\Delta V_1 = V_{P1} - V_{C1} = \sqrt{\frac{\mu}{a} \left(\frac{1+e}{1-e} \right)} - \sqrt{\frac{\mu}{r_1}}$$

$$\Delta V_2 = V_{C2} - V_{A2} = \sqrt{\frac{\mu}{r_2}} - \sqrt{\frac{\mu}{a} \left(\frac{1-e}{1+e} \right)}$$

TEMPO di VOLO: mezzo PERIODO $T_{0.5} = \pi \sqrt{\frac{a^3}{\mu}}$

ESEMPI:

Satellite con $e=0$ e $r = 1.2769 \times 10^4$ Km.

Calcolare ΔV minima per raddoppiare altitudine.

$$r_1 = 1.2769 \times 10^4 \text{ Km } (= 2 R_{\oplus})$$

$$r_2 = 3 R_{\oplus} = 1.9154 \times 10^4 \text{ Km}$$

$$a = \frac{5}{2} R_{\oplus} = 1.5961 \times 10^4 \text{ Km} \quad e = 0.2$$

$$V_{c1} = \sqrt{\frac{\mu}{r_1}} = 5.595 \times 10^3 \text{ m/s} \quad V_{p1} = 6.129 \times 10^3 \text{ m/s}$$

$$\Delta V_1 = 0.534 \times 10^3 \text{ m/s}$$

$$V_{c2} = 4.569 \times 10^3 \text{ m/s}$$

$$V_{a2} = 4.086 \times 10^3 \text{ m/s}$$

$$\Delta V_2 = 0.482 \times 10^3 \text{ m/s}$$

$$\bullet \Delta V_{\text{tot}} = 1.016 \times 10^3 \text{ m/s}$$

TRASFERIMENTO di Hohmann su MARS

$$a = \frac{1+1.5}{2} = 1.25 \text{ AU} \quad e = 0.2$$

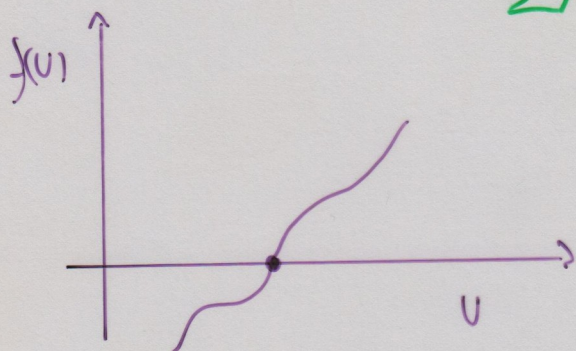
$$T_{\text{OF}} = \frac{T_{\text{orb}}}{2} = 255 \text{ giorni} \sim 8.5 \text{ mesi}$$

ALGORITMO NUMERICO per la RAPIDA CONVERGENZA di EQ. KEPLERO

$$\begin{cases} f(U) = U - e \sin U - M = 0 \\ f'(U) = 1 - e \cos U > 0 \quad \text{per } e \leq 1 \end{cases}$$



SOLUZIONE
UNICA



METODO di
Newton-Raphson
(v. 256 Numerical
Recipes,

- $x_0 = x \quad (=U)$

$$f(x+\delta) = f(x) + f'(x) \cdot \delta + \dots = 0$$

- $x_1 = x + \delta \quad \text{con } \delta = -\frac{f(x)}{f'(x)}$

⋮

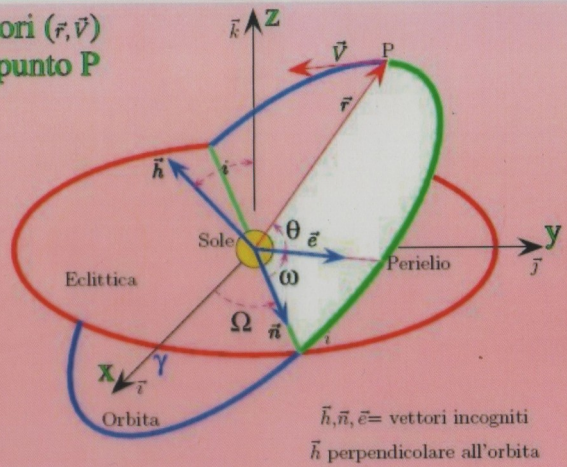
- $x_{i+1} = x_i + \delta = x_i - \frac{f(x_i)}{f'(x_i)}$

CONVERGENZA QUADRATICA! molto rapida.

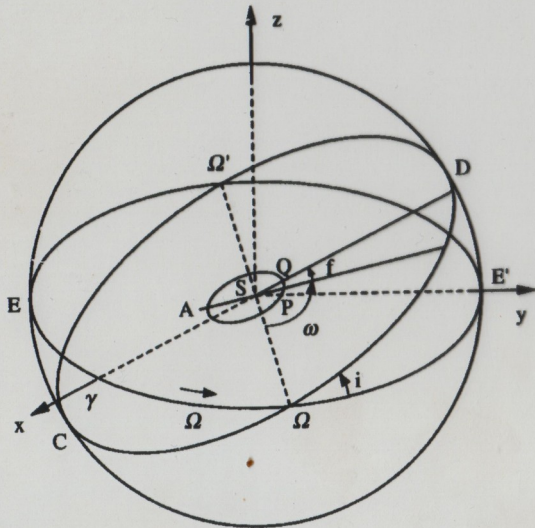
(v. 35 D-M, metodo Dancy, convergenza quadratica!)

Orbital elements

Vettori (\vec{r}, \vec{v}) del punto P



A semimajor axis,
e eccentricity,
 i inclination,
 M mean anomaly,
 ω pericenter argument,
 Ω node longitude



-7-

TRASFORMAZIONI

CASO
PIANO

$$a, e, M \longleftrightarrow \bar{x}, \bar{v}$$

$$1) \text{ da } M \text{ a } U \quad U - e \sin U = M$$

$$2) r = a(1 - e \cos U) \\ \text{tg}\left(\frac{f}{2}\right) = \left(\frac{1+e}{1-e}\right)^{\frac{1}{2}} \text{tg}\left(\frac{U}{2}\right) \Rightarrow r, f$$

$$3) x = r \cos f \quad y = r \sin f \\ x = a(\cos U - e) \quad y = a\sqrt{1-e^2} \sin U$$

$$\left(\frac{dU}{dt} = \frac{\mu}{1-e \cos U}\right)$$

$$4) v_x = -\frac{ma \sin U}{1 - e \cos U} \quad v_y = \frac{ma \sqrt{1-e^2} \cos U}{1 - e \cos U}$$

$$-1) r = \sqrt{x^2 + y^2 + z^2} \quad v = \sqrt{v_x^2 + v_y^2 + v_z^2}$$

$$-2) C = \frac{1}{2} v^2 - \frac{\mu}{r} = -\frac{\mu}{2a}$$

$$-3) h = |\bar{r} \times \bar{v}| = \sqrt{\mu a (1-e^2)}$$

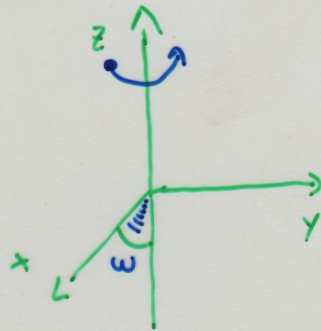
$$-4) r = \frac{a(1-e^2)}{1+e \cos f} \quad \dot{r} = \frac{mae \sin f}{\sqrt{1-e^2}} = \frac{\bar{v} \cdot \bar{r}}{r}$$

$$-5) \text{tg}\left(\frac{f}{2}\right) = \left(\frac{1+e}{1-e}\right)^{\frac{1}{2}} \text{tg}\left(\frac{U}{2}\right) \quad U - e \sin U = M$$

ORBITA NELLO SPAZIO 3D

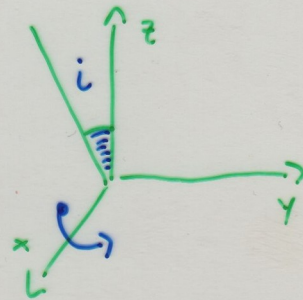
$$M_1 = \begin{pmatrix} \cos \omega & -\sin \omega & 0 \\ \sin \omega & \cos \omega & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{array}{l} \text{Attorno} \\ \text{asse} \\ z \end{array}$$

$\omega =$ argomento pericentro



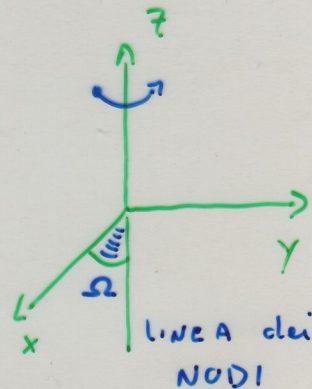
$$M_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos i & -\sin i \\ 0 & \sin i & \cos i \end{pmatrix} \quad \begin{array}{l} \text{Attorno} \\ \text{asse} \\ x \end{array}$$

$i =$ inclinazione



$$M_3 = \begin{pmatrix} \cos \Omega & -\sin \Omega & 0 \\ \sin \Omega & \cos \Omega & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \begin{array}{l} \text{Attorno} \\ \text{asse} \\ z \end{array}$$

$\Omega =$ longitudine nodo



$$\tilde{\omega} = \omega + \Omega$$

$$\begin{pmatrix} X \\ Y \\ Z \end{pmatrix} = M_3 M_2 M_1 \begin{pmatrix} r \cos f \\ r \sin f \\ 0 \end{pmatrix} =$$

$$= \begin{pmatrix} r \cos \Omega \cos(\omega + f) - r \sin \Omega \sin(\omega + f) \cos i \\ r \sin \Omega \cos(\omega + f) + r \cos \Omega \sin(\omega + f) \cos i \\ r \sin(\omega + f) \sin i \end{pmatrix}$$

TRASFORMAZIONE da ELEMENTI KEPLERIANI a COORDINATE CARTESIANE.

$$a, e, i, \omega, \Omega, M \rightarrow \bar{x}, \bar{v}$$

1) Eq. Keplera $U - e \sin U = M \rightarrow f$

2) $x = a(\cos U - e)$
 $y = a\sqrt{1-e^2} \sin U$

3) $V_x = -\frac{ma \sin U}{1 - e \cos U}$
 $V_y = \frac{ma \sqrt{1-e^2} \cos U}{1 - e \cos U}$

$$a, e, M \rightarrow (x, y, 0) (V_x, V_y, 0)$$

4)

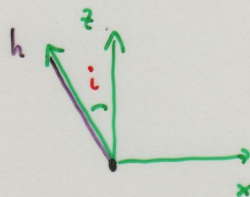
$$\begin{pmatrix} X \\ Y \\ Z \end{pmatrix} = M_3(\Omega) \cdot M_1(i) \cdot M_3(\omega) \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$$\begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix} = \dots \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix} = \begin{pmatrix} V_x \\ V_y \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} x \\ y \\ 0 \end{pmatrix}$$

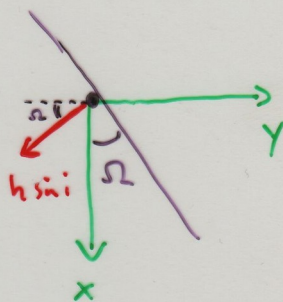
10-
bSAPENDO x, y, z TROVARE GLI ANGOLI ORBITALI
 v_x, v_y, v_z 52-63
D-M

$$- (i) \quad h \cos i = h_z$$



$$- (\Omega) \quad \begin{cases} h \sin i \sin \Omega = \pm h_x \\ h \sin i \cos \Omega = \mp h_y \end{cases}$$

$$\operatorname{tg} \Omega = -\left(\frac{h_x}{h_y}\right)$$



$$- (\omega) \quad \begin{cases} \sin(\omega + f) = \frac{z}{R \sin i} \\ \cos(\omega + f) = \frac{x}{R \cos \Omega} + \frac{z}{R} \frac{\sin \Omega}{\cos \Omega} \frac{\cos i}{\sin i} \end{cases}$$

$$\Downarrow$$

$$\omega + f \Rightarrow \omega$$

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = M_3 M_2 M_1 \begin{pmatrix} R \cos f \\ R \sin f \\ 0 \end{pmatrix}$$

12-
b TRASFORMAZIONE da COORDINATE CARTESIANE \Rightarrow
ELEMENTI KEPLERIANI

$$1) \quad r = \sqrt{x^2 + y^2 + z^2} \quad v = \sqrt{v_x^2 + v_y^2 + v_z^2} \quad \dot{i} = \frac{\vec{v} \cdot \vec{r}}{r}$$

$$C = \frac{1}{2} v^2 - \frac{\mu}{r} \quad C = -\frac{\mu}{2a} \quad \vec{h} = \vec{r} \times \vec{v} = h \hat{h} \rightarrow \boxed{a, e}$$

$$h^2 = \mu a (1 - e^2)$$

$$2) \quad h \cos i = h_z \quad \boxed{i = \arccos\left(\frac{h_z}{h}\right)}$$

$$3) \quad \begin{aligned} h \sin i \sin \Omega &= \mp h_x \\ h \sin i \cos \Omega &= \mp h_y \end{aligned} \quad \boxed{\tan(\Omega) = -\left(\frac{h_x}{h_y}\right)}$$

$$4) \quad \begin{aligned} \cos f &= \frac{a(1-e^2)}{r \cdot e} - \frac{1}{e} \\ \sin f &= \frac{r \sqrt{1-e^2}}{mae} \end{aligned} \quad \boxed{\tan(f) = \frac{r \sqrt{1-e^2}}{ma(a(1-e^2) - r)}}$$

$$5) \quad \sin(\omega + f) = \frac{z}{r \sin i} \quad \Rightarrow \omega + f \rightarrow \boxed{\omega}$$

$$\cos(\omega + f) = \frac{x}{r \cos \Omega} + \frac{z}{r} \frac{\sin \Omega}{\cos \Omega} \frac{\cos i}{\sin i}$$

$$6) \quad \tan\left(\frac{U}{2}\right) = \left(\frac{1-e}{1+e}\right)^{\frac{1}{2}} \tan\left(\frac{f}{2}\right) \Rightarrow U \Rightarrow$$

$$M = U - e \sin U \quad \rightarrow \boxed{M}$$

10) PROBLEMA 4: Calcolare l'intervallo tra 2 congiunzioni di Marte e Terra e mostrare che la distanza minima alla congiunzione può essere di un giorno 2.

$$a_M = 1.5236631 \text{ AU}$$

$$a_T = 1.000 \dots$$

$$M_M = 9.146 \times 10^{-3} \frac{1}{\text{day}}$$

$$M_T = 1.710 \times 10^{-2} \frac{1}{\text{day}}$$

$$T_M = 686.96 \text{ day}$$

$$T_T = 365.25 \text{ day}$$

$$\frac{T_M}{T_T} \approx 1.88 \text{ circa } 2$$

$$M_M \Delta t = M_T \Delta t - 2\pi \Rightarrow \Delta t = \frac{2\pi}{M_T - M_M} \approx 780 \text{ day}$$

af.

per.

$$D_{\min} = -a_T(1+e_T) + a_M(1-e_M) = 0.0365 \text{ AU}$$

$$D_{\max} = -a_T(1-e_T) + a_M(1+e_M) = 0.0683 \text{ AU}$$

per.

af.

$$G = 6.6743 \cdot 10^{-11} \frac{\text{m}^3}{\text{kg s}^2}$$

$$K = 0.0172021$$

$$GM_\odot = K^2 \left[\frac{\text{AU}}{\text{day}} \right]^3 \approx 7.9591 \times 10^{-6}$$