

Soluzione del problema 3

(a)

Essendo la guida liscia, la reazione vincolare è sempre normale allo spostamento infinitesimo lungo la traiettoria, dunque:

$$W_{BP} = 0 \text{ J}$$

(b)

$$W_{ad} = -\mu N d = -\mu m g d$$

$$\frac{1}{2} k (\Delta x)^2 + W_{ad} = \frac{1}{2} m v_B^2 \quad \Rightarrow \quad v_B = \sqrt{\frac{k}{m} (\Delta x)^2 - 2 \mu g d} = 3.3 \text{ m/s}$$

(c)

$$\frac{1}{2} m v_B^2 = m g h \quad \Rightarrow \quad h = \frac{v_B^2}{2g} = \frac{k}{2gm} (\Delta x)^2 - \mu d = 0.56 \text{ m}$$

(d)

$$\begin{aligned} \frac{1}{2} m v_P^2 &= m g R \cos \theta \quad \Rightarrow \quad \frac{v_P^2}{R} = 2 g \cos \theta \\ N_1 - m g \cos \theta &= 2 m g \cos \theta \quad \Rightarrow \quad N_1 = 3 m g \cos \theta = 38.2 \text{ N} \end{aligned}$$

Soluzione del problema 4

(a)

$$a_T = \frac{F_T}{m} = \frac{A}{m} t$$

(b)

$$v = \frac{A}{m} \int_0^t t dt = \frac{A}{2m} t^2$$

$$a_N = \frac{v^2}{R} = \frac{A^2}{4m^2 R} t^4$$

$$a = \sqrt{a_T^2 + a_N^2} = \frac{A}{m} t \sqrt{1 + \frac{A^2 t^6}{16m^2 R^2}}$$

(c)

$$x_1 = \frac{A}{2m} \int_0^{t_1} t^2 dt = \frac{A}{6m} t_1^3 = n_1 2\pi R$$

$$t_1 = \left(\frac{12n_1 \pi m R}{A} \right)^{1/3} = 1.5 \text{ s}$$

(d)

$$x = \frac{A}{6m} t^3 \quad v = \frac{A}{2m} t^2$$

$$T_{max} = \frac{m v^2}{R} = \frac{A^2}{4Rm} t^4 \Rightarrow t = \left(\frac{4m R T_{max}}{A^2} \right)^{1/4}$$

$$x_{max} = \frac{A}{6m} \left(\frac{4m R T_{max}}{A^2} \right)^{3/4} \Rightarrow n_{max} = \frac{x_{max}}{2\pi R} = \frac{A}{12\pi m R} \left(\frac{4m R T_{max}}{A^2} \right)^{3/4} = 8.67$$